

Leit 7: Feedback stabilization of angular momentum system.

$$\begin{aligned}
 \text{SME: } \left\{ \begin{aligned}
 d\mathbf{p}_t &= -i[\omega J_z + \mu J_y, \mathbf{p}_t] dt + \mu (J_z \mathbf{p}_t J_z - J_z^2 \mathbf{p}_t / 2 - \mathbf{p}_t J_z^2 / 2) dt \\
 &\quad + \sqrt{J_z} (\mathbf{J}_z \mathbf{p}_t + \mathbf{p}_t \mathbf{J}_z - 2 \text{Tr}(\mathbf{J}_z \mathbf{p}_t) \mathbf{p}_t) dW_t. \\
 &= \boxed{F(\mathbf{p}_t)} dt + \boxed{\sqrt{J_z} G(\mathbf{p}_t)} dW_t
 \end{aligned} \right.
 \end{aligned}$$

$$\mathcal{P} \in \mathcal{S} = \{ \mathbf{p} \in \mathbb{C}^{N \times N} \mid \mathbf{p} = \mathbf{p}^* \geq 0, \text{Tr}(\mathbf{p}) = 1 \}$$

$$\mathbf{J}_z = \begin{bmatrix} J & & & \\ & J-1 & & \\ & & \ddots & \\ & & & -J+1 \\ & & & & -J \end{bmatrix}, \quad J = \frac{N-1}{2}, \quad \mathbf{J}_y = \begin{bmatrix} 0 & -i c_1 & & \\ i c_1 & 0 & & \\ & & \ddots & \\ & & & 0 & -i c_J \\ & & & i c_J & 0 \end{bmatrix}$$

$c_1 = \frac{\sqrt{(2J+1)M}}{2}$

$\omega \geq 0$, $\mu \in (0, 1]$, $\mu > 0$.

1) Asymptotic feedback stabilization

Ref: 1. R. van Handel, et al. IEEE TAC 2005

2. M. Mirrahimi, R. van Handel, SIAM J contr. opt 2007

1) 2-dim.

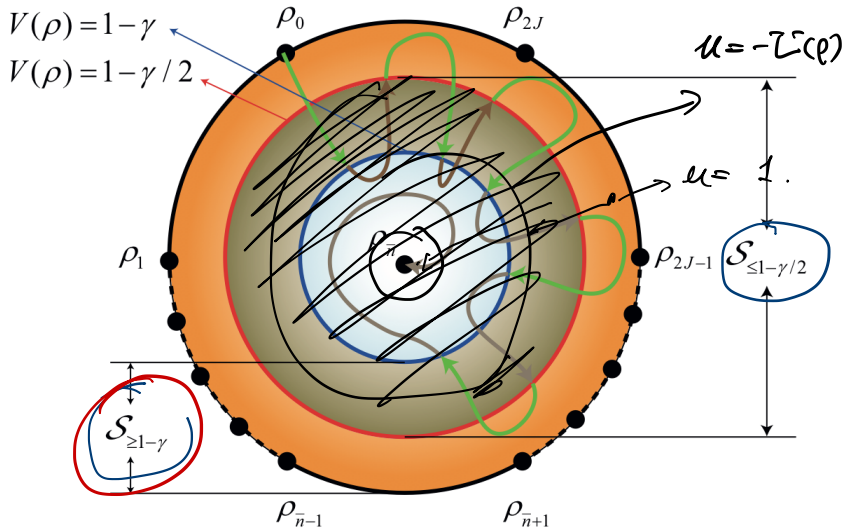
$$\mathbf{p} = \frac{\beta + x \mathbf{e}_1 + y \mathbf{e}_2 + z \mathbf{e}_3}{2} = \begin{bmatrix} 1+\delta & x-iy \\ x+iy & 1-\delta \end{bmatrix}$$

(x, y, δ) ,

$$\mu_t = z(1+\delta) + \beta x_t, \quad \bar{\mathbf{p}} = \mathbf{p}_y = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \leftrightarrow (0, 0, -1)$$

$$\mu(\mathbf{p}_y) = 0, \quad \mu(\mathbf{p}_x) \neq 0, \quad \mathbf{p}_x = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \leftrightarrow (0, 0, 1)$$

\Rightarrow Markov, SOSTODS, $\Rightarrow \boxed{V}$, $2V \leq 0 \Rightarrow \mathbf{p}_t \rightarrow \bar{\mathbf{p}}$.



\Rightarrow N -dim. Spin- J .

$u \equiv 0$, $\bar{E} = \{\rho_0, \dots, \rho_{2J}\}$, $\rho_{\bar{n}} \in \bar{E}$, ρ_k antipodal.
 $k \neq \bar{n}$: eigen state

\rightarrow target state.

$$\begin{bmatrix} 1 & & \\ & \ddots & \\ & & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & & \\ & \ddots & \\ & & 1 \end{bmatrix}$$

$$\bar{V}(\rho) = 1 - \text{Tr}(\rho \rho_{\bar{n}}) \in [0, 1]$$

$$\bar{V}(\rho) = 0 \text{ iff } \rho = \rho_{\bar{n}}$$

$$\bar{V}(\rho_k) = 1 \quad k \neq \bar{n}$$

$$\forall \epsilon \in (0, 1), \quad S_{\geq 1 - \epsilon} = \{\rho \in S \mid 1 - \epsilon \leq \bar{V}(\rho) \leq 1\}$$

$$S_{\leq 1 - \frac{\epsilon}{2}} = \{\rho \in S \mid 0 \leq \bar{V}(\rho) \leq 1 - \frac{\epsilon}{2}\}$$

Step 1: $\exists \delta \in (0, 1)$, s.t. $S_{\geq 1-\delta}$ is not invariant under $u=1$.
 \rightarrow probability of exiting $S_{\geq 1-\delta}$ is > 0 .

Proof: Support theorem: C Stroock, Vasardolou, 1972).
 $\int_0^t dW_t \iff \text{Str. SDE} \iff \text{Stro. SDE} \leftarrow \text{all piecewise constant funts. } \mathbb{R}^n \rightarrow \mathbb{R}^n$

$\exists T < \infty$, $\mathbb{P}(X_T \in B_r(\bar{x}) \mid X_0 = x) > 0$.
 \iff ODE.
 $\exists \epsilon < T < \infty, v_t \in V$.
 $\{ (T, x, v) \in B_r(\bar{x})$

Step 2: a.e. $\omega \in \Omega$, $P_t(\omega)$ can exit $S_{\geq 1-\delta}$ under $u=1$ in $T_1(\omega) < \infty$.

Proof: Dynkin estimation.

$$\sup_{P_0 \in S_{\geq 1-\delta}} \mathbb{E}_{P_0}[\tau] \leq \frac{T}{1 - \sup_{P_0 \in (S_{\geq 1-\delta})} \mathbb{P}_{P_0}(\tau \geq T)} \leq \frac{T}{\beta} < \infty$$

first exiting time from $S_{\geq 1-\delta}$.

S is compact.

- $S_{\geq 1-\delta}$ is compact.
- P_t is Feller continuous.

$\exists \beta > 0, \sup_{P_0 \in S_{\geq 1-\delta}} \mathbb{P}_{P_0}(\tau \geq T) \leq 1 - \beta < 1$

$$\mathbb{P}_e(\tau < \infty) = 1.$$

step 3: a.e. $\omega \in \Omega$, $\exists T_2(\omega) < \infty$, $\forall t \geq T_2(\omega)$, under a suitable feedback laws (u_t) , $P_t(\omega)$ will stay in $S_{\leq 1-\delta/2}$ and never exit.

Proof:
$$V(p) = 1 - \text{Tr}(p \bar{p}_\pi) \quad u(p) = -L(p)$$

$$L V(p) = u(p) \underbrace{\text{Tr}(i [J_g, p] \bar{p}_\pi)}_{L(p)} \leq -L(p)^2 \leq 0$$

$$L(p) \leq 0 \quad \forall p \in \bar{E}.$$

$$p \in S_{\leq 1-\delta/2} \quad (\ni p_\pi). \quad u(p) = -L(p).$$

τ first exiting time from $S_{\leq 1-\delta/2}$.

$$\begin{aligned} \mathbb{E}[V(p_{\tau \wedge t})] &= V(p_0) + \mathbb{E}\left[\int_0^{\tau \wedge t} L V(p_s) ds\right] \\ &\leq V(p_0) \quad \leq \quad \leq \\ &\quad \quad \quad \underline{(p_0 \in S_{\leq 1-\delta})} \end{aligned}$$

\Rightarrow Supermartingale inequality:

$$\begin{aligned} \mathbb{P}\left(\sup_{t \geq 0} V(p_t) \geq 1 - \delta/2\right) &= \mathbb{P}\left(\sup_{t \geq 0} V(p_{t \wedge \tau}) \geq 1 - \delta/2\right) \\ &\leq \frac{V(p_0)}{1 - \delta/2} \leq \frac{1 - \delta}{1 - \delta/2} < 1. \end{aligned}$$

$S_{\geq 1-\delta/2}$ n time.

- Strongly Markov property.
 - Borel Cantelli lemma
- $\Rightarrow \mathbb{P}(T_n^{(\geq 1-\delta/2)} < \infty, \text{ for infinitely many } n) = 0.$
- $\Rightarrow \sum \mathbb{P}(T_n^{\geq 1-\delta/2} < \infty) < \infty.$

step: $\forall p_0 \in S, p_t \xrightarrow{\text{a.s.}} p_{\bar{n}}$ under a suitable feedback laws.

Proof: $\tilde{V}(p) = 1 - \text{Tr}(p p_{\bar{n}}^2) \in [0, 1] \Rightarrow$ via LaSalle thm

\Downarrow

$\lim \mathbb{E} \tilde{V} \Rightarrow 0$

\Downarrow

$p_t \rightarrow p_{\bar{n}} \text{ a.s.}$

Thm (M.M. R.v. ft 2007)

- $u(p) = -\tilde{V}(p)$ for $p \in S_{< 1-\delta}$
- $u(p) = 1$ for $p \in S_{\geq 1-\delta/2}$.
- for $p \in B = \{ \delta/2 < \text{Tr}(p p_{\bar{n}}) < \delta \}$, then $u(p) = -\tilde{V}(p)$, if p_t enter B through $\tilde{V}(p) = 1 - \delta$, and $u(p) = 1$ otherwise.

Then, $p_t \xrightarrow{\text{a.s.}} p_{\bar{n}}$.

Improvements:

1. step 1,2 \rightarrow arbitrary $\delta > 0$.
2. step 4 \rightarrow local Lyapunov argument, estimate the rate of convergence.
3. Provide the sufficient conditions on $u(p)$, $p_t \xrightarrow[\text{a.s.}]{\text{exp.}} p_{\bar{n}}$.

27 Exponential feedback stabilization.

Ref: Liang, N. Arini, P. Mason, Siam J. Control, opt. 2019.

⊙ Preliminary results (without proof).

Lemma: Assume $\hat{u} \in C^1(S, \mathbb{R})$. The set of all positive-definite matrices is a.s. invariant for SDE.

$$\text{int}(S) := \{p \in S \mid p > 0\} \stackrel{!}{\leftarrow}$$

Lemma: $\frac{\eta=1}{u \in C^1}$, $\partial S := \{p \in S \mid \det(p) = 0\}$ is invariant.

⇒ Prop: $f \in (0, 1)$, $u \in C^1$, $u(p_\pi) = 0$, $\forall u, G(p) \neq 0$ or $\forall u, \hat{F}(p) \neq 0$ for any $p_0 \in \partial S \setminus p_\pi \mid p_{i_k} = 0$ for some k and $u(p) = 0$.

Then, $\forall p_0 \in \partial S \setminus p_\pi \mid p_{i_k} = 0$ for some $k \in \{1, \dots, n\}$, $\forall \varepsilon > 0$.
 \exists at most one $p(t)$ starting from p_0 which lies in ∂S .
 For any other $p_0 \in \partial S \setminus p_\pi$, $\forall v_t \in V$, $p(t) > 0$ for $t > 0$.



$$V = \sqrt{p_{n,n}} \mathbb{R}.$$

$$\dot{p} = F(p) dt + \sqrt{G(p)} dW_t. \quad \text{SDE}$$

$$\frac{dp_v}{dt} = \hat{F}(p) + \sqrt{G(p)} v_t. \quad \text{ODE. } v_t \in V.$$

⊙ Pb: $f \in (0, 1)$ cond. on \hat{u} $p(t) > 0$ for $t > 0$, a.s. for all $p_0 \in \partial S \setminus p_\pi$? ←

$$J_{\bar{n}} = \begin{bmatrix} J & & & \\ & \ddots & & \\ & & J_{\bar{n}} & \\ & & & \ddots \\ & & & & -J \end{bmatrix}$$

$$J_{\bar{n}} \cdot p_{\bar{n}} = (J - \bar{n}) p_{\bar{n}}$$

1. Reachability of ODE.

Lemma. $u(p_{\bar{n}}) = 0, u \in C^1$. Suppose $\exists v \in V$ s.t., for any $p \in \{p_{k_1 k_2} = 0 \text{ for some } k_1, k_2, u(p_{k_1 k_2}) \neq 0 \text{ for } t \in (0, \infty)\}$ for $\varepsilon < \infty$.

Assume, $\forall p \in \{J - \bar{n} - \text{Tr}(J_{\bar{n}} p) = 0\} \setminus p_{\bar{n}}$.

$$2\gamma M \text{Var}(p) p_{\bar{n}, \bar{n}} > u(p) \text{Tr}(i \mathbb{Z} J_{\bar{n}} p J p_{\bar{n}})$$

$$= \text{Tr}(J_{\bar{n}}^2 p) - \text{Tr}(J_{\bar{n}} p)^2 \stackrel{\text{C.S.}}{\geq} 0.$$

$\text{Var}(p) = 0$ iff $p \in \bar{E} = \{e_1, \dots, e_j\}$



Then, $\forall p \in S$, and $\forall r > 0, \exists T \in (0, \infty)$ s.t., $p_r(T) \in B_r(p_{\bar{n}})$.

$$v_e = \frac{K}{p_{\bar{n}} p_{\bar{n}, \bar{n}}}$$

Proof: $\text{Tr}(p p_{\bar{n}}) = 1 \iff p = p_{\bar{n}}$.

ODE. $\overset{p_{\bar{n}, \bar{n}}}{(p_r(t))_{\bar{n}, \bar{n}}} = \overset{(\Delta \bar{n}) < R.}{\Delta \bar{n}(p_r)} + 2\gamma M \overset{p_{\bar{n}}(p_r)}{p_{\bar{n}}(p_r)} \overset{(p_r)_{\bar{n}, \bar{n}}}{(p_r)_{\bar{n}, \bar{n}}} \overset{v_e}{v_e}$

$$\Delta \bar{n}(p) = 2\gamma M (\text{Tr}(J_{\bar{n}}^2 p) - \text{Tr}(J_{\bar{n}} p)^2) p_{\bar{n}, \bar{n}} - u(p) \text{Tr}(i \mathbb{Z} J_{\bar{n}} p J p_{\bar{n}})$$

$$+ 4\gamma M p_{\bar{n}}(p) \text{Tr}(p J_{\bar{n}}) p_{\bar{n}, \bar{n}}$$

$$p_{\bar{n}}(p) = J - \bar{n} - \text{Tr}(J_{\bar{n}} p)$$

$$p_{\bar{n}}(p) = 0$$

$$J - \bar{n} = \text{Tr}(J_{\bar{n}} p)$$

$$P_{\bar{n}}(\varphi) = I - \bar{n} - \text{Tr}(J\varphi)$$

⊙. assumption $\Rightarrow \exists v, u(\varphi) \neq 0 \xrightarrow{\text{Prop 3}} P_{\bar{n}, \bar{n}}(a) > 0$
 $\Rightarrow \dots$ suppose $\underline{P_{\bar{n}, \bar{n}}(0)} > 0$. [\dots]

⊙. 1. $\bar{n} = 0$, $P_{\bar{n}}(\varphi) = J - \text{Tr}(J\varphi) = \sum_{n=0}^{2J} n \cdot P_{n,n} \geq 0$, $P_0(\varphi) = 0 \nRightarrow \varphi = \overset{0}{0}$
 $\bar{n} = 2J$, $P_{\bar{n}}(\varphi) = -J - \text{Tr}(J\varphi) = -2J + \sum_{n=0}^{2J} n P_{n,n} \leq 0$, $P_{2J}(\varphi) = 0 \nRightarrow \varphi = \overset{2J}{2J}$
 $\left. \begin{array}{l} 0 \leq P_{n,n} \leq 1 \\ \sum_{n=0}^{2J} P_{n,n} = 1 \end{array} \right\} \text{ [} \begin{array}{c} 0 \\ \dots \\ 1 \end{array} \text{]}$

$$\Rightarrow v = \frac{K}{P_{\bar{n}}(\varphi) P_{n, \bar{n}}}, \quad K \text{ sufficiently large.}$$

$$\Rightarrow \forall r > 0, \exists T, P_r(T) \in B_r(P_{\bar{n}})$$

2. $\bar{n} \in \{1, \dots, 2J-1\}$.

$$P_{\bar{n}}(\varphi) \neq 0.$$

$$P_{\bar{n}}(\varphi) = 0? \Rightarrow (P_{r(t)})_{\bar{n}, \bar{n}} = \Delta_{\bar{n}}(\varphi) = 2JM \text{Var}(\varphi) P_{\bar{n}, \bar{n}} - u(\varphi),$$

Trickily, (16)

> 0
 \uparrow
 assumption.

⊙ Reachability of SMB.

Dynkin estimation.
 $P_n \rightarrow$ Feller continuous
 $S \setminus B_0(P_{\bar{n}})$ is compact

#

$$\inf_{t \geq 0} P_t \in B_0(P_{\bar{n}})$$

\downarrow

$$P_{P_0}(\tau < \infty) = 1.$$