

# Introduction to quantum feedback control

CY-McGill Mathematical Physics Weekly Seminar

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# Outline

- 1 Input-output model for homodyne detection
- 2 Conditional expectation and Bayes formula
- 3 Quantum filtering theory

# Input-output model for homodyne detection

## Input-output model for homodyne detection

### References :

- 1 K. R. Parthasarthy, "*An introduction to quantum stochastic calculus*", 1992.
- 2 A. Barchielli, "*Continual measurements in quantum mechanics and quantum stochastic calculus*", In *Open Quantum Systems III* (pp. 207-292), 2006.
- 3 L. Accardi, Y. G. Lu, I. Volovich, "*Quantum theory and its stochastic limit, Ch 4-6*", Springer, 2002.
- 4 L. Bouten, R. van Handel, M. James, "*An introduction to quantum filtering*", SIAM. J. Control Optim, 2007.
- 5 L. Bouten, R. van Handel, "*On the separation principle in quantum control*", *Quantum Stoch. Inf.* (pp. 206-238), 2008.

# Input-output model for homodyne detection <sup>1 2</sup>

$$\text{H-P equation : } dU_t = (L_t dA_t^\dagger - L_t^* dA_t - \frac{1}{2} L_t L_t^* dt + iH_t dt) U_t, \quad U_0 = \mathbb{1}.$$

## Evolution of system :

- System observable (H.P.) :  $j_t(X) = U_t^*(X \otimes \mathbb{1})U_t$
- $dj_t(X) = j_t(\mathcal{L}^*(X))dt + j_t([X, L_t])dA_t^\dagger + j_t([L_t^*, X])dA_t$

## Evolution of field :

- $Z_t := A_t + A_t^\dagger$  is essentially selfadjoint on  $\mathcal{E}$
- $\bar{Z}_t$  is quantum Brownian motion (selfadjoint+commutative)
- Observation process (H.P.) :  $Y_t = U_t^* Z_t U_t$

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1. L. Accardi, Y. G. Lu, I. Volovich, "Quantum theory and its stochastic limit, Ch 4.26", 2002.  
2. A. Barchielli, "Continual measurements in Q.M. and quantum stochastic calculus, Sec 2.2".

# Nondemolition property

## Lemma

$\{Z_t\}$  is a commutative process and  $Z_t := \text{vN}\{Z_s | s \leq t\}$  is commutative.

## Lemma : self-nondemolition property <sup>1</sup>

$\mathcal{Y}_t := \text{vN}\{Y_s | 0 \leq s \leq t\}$  is commutative for all  $t \in [0, T]$  with  $T < \infty$ .

*Proof.*

- 1  $E \in Z_s$  : an arbitrary projection in the range of the spectral measure of  $Z_s$
- 2 Quantum Itô's formula on :  $j_t(E) = U_t^* E U_t$
- 3  $j_t(E) = j_s(E) + \int_s^t j_r([L^*, E]) dA_r + \int_s^t j_r([E, L]) dA_r^\dagger + \int_s^t j_r(\mathcal{L}^*(E)) dr$
- 4  $E = \mathbb{1} \otimes E$  commutes with  $L = L \otimes \mathbb{1}$  and  $H = H \otimes \mathbb{1}$
- 5  $j_t(E) = j_s(E)$  for any  $0 \leq s \leq t$
- 6 Bounded functional calculus  $\Rightarrow \xi_{Y_s} = U_s^* \xi_{Z_s} U_s$  ( $\xi$  is the spectral measure)
- 7  $Z_t$  commutative  $\Rightarrow \mathcal{Y}_t$  commutative

**Remark :**  $\{Y_t\}$  is commutative  $\Rightarrow y(t) = \text{vN}(Y_t)$  classical stochastic process

1. L. Bouten, R. van Handel, "On the separation principle in quantum control, Prop 2.1", 2008.

# Nondemolition property

Lemma : nondemolition property <sup>1</sup>

$j_t(X) \in \mathcal{Y}'_t$  for all  $X \in \mathcal{B}(\mathcal{H}_S)$  and  $t \in [0, T]$  with  $T < \infty$ .

*Proof.*

1  $\mathcal{Y}_t = U_t^* Z_t U_t$

2  $j_t(X) = U_t^*(X \otimes \mathbb{1})U_t \in U_t^*(\mathcal{B}(\mathcal{H}_S) \otimes \mathbb{1})U_t$

3  $\mathcal{B}(\mathcal{H}_S) \otimes \mathbb{1}$  commutes with  $Z_t = \text{vN}\{\mathbb{1} \otimes Z_s | 0 \leq s \leq t\}$

4  $j_t(X) \in \mathcal{Y}'_t$

**Remark :** Nondemolition property ensures the existence of conditional expectation.

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1. L. Bouten, R. van Handel, "On the separation principle in quantum control, Prop 2.1", 2008.

# Conditional expectation and Bayes formula

## Conditional expectation and Bayes formula

### References :

- 1 R. van Handel, "*Filtering, stability, and robustness*", Ph.D. Thesis, 2007.
- 2 L. Bouten, R. van Handel, M. James, "*An introduction to quantum filtering*", SIAM. J. Control Optim, 2007.
- 3 L. Bouten, R. van Handel, "*On the separation principle in quantum control*", Quantum Stoch. Inf. (pp. 206-238), 2008.
- 4 M. Takesaki, "*Conditional expectations in von Neumann algebras*", Journal of Functional Analysis, 1972.

# Classical filtering theory <sup>1</sup>

## Classical filtering theory on $(\Omega, \mathcal{F}, \mathbb{P})$ : reference probability method

- 1 Conditional expectation :  $\mathbb{E}(X|\mathcal{G})$  with  $\mathcal{G} \subset \mathcal{F}$
- 2 Optimal estimation :  $\mathbb{E}(X - \mathbb{E}(X|\mathcal{G}))^2 = \min_{Y \in L^2(\mathcal{G})} \mathbb{E}(X - Y)^2$ .
- 3 Bayes formula :  $\mathbb{E}(X|\mathcal{G}) = \mathbb{E}^{\mathbb{Q}}(XM|\mathcal{G})/\mathbb{E}^{\mathbb{Q}}(M|\mathcal{G})$  with  $M = d\mathbb{P}/d\mathbb{Q}$
- 4 Girsanov theorem  $\Rightarrow$  define the reference probability  $\mathbb{Q}_t$  s.t.  $M_t = d\mathbb{P}/d\mathbb{Q}_t$
- 5 Kallianpur-Striebel formula  $\mathbb{E}(f(x_t)|\mathcal{F}_t^Y) = \mathbb{E}^{\mathbb{Q}_t}(M_t f(x_t)|\mathcal{F}_t^Y)/\mathbb{E}^{\mathbb{Q}_t}(M_t|\mathcal{F}_t^Y)$
- 6 Kushner-Stratonovich equation  $\pi_t(f) := \mathbb{E}(f(x_t)|\mathcal{F}_t^Y)$

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1. J. Xiong, "An introduction to stochastic filtering theory, Ch5", Oxford, 2008



# Quantum conditional expectation

## Restrictions on quantum conditional expectation :

- 1 observations that is conditioned on must be commutative
  - It ensures that the 'observations' can be observed in a realization
  - It is guaranteed by self-nodemolition property.
- 2 conditioned observables must commute with (commutative) observations
  - It ensures that the joint statistic of events and observations is well defined
  - It is guaranteed by nodemolition property.

## Definition : quantum conditional expectation

Let  $(\mathcal{A}, \varphi)$  be a quantum probability space,  $\mathcal{B} \subset \mathcal{A}$  be a commutative von Neumann subalgebra. Then  $\varphi(\cdot|\mathcal{B}) : \mathcal{B}' \rightarrow \mathcal{B}$  is called (a version of) the conditional expectation given  $\mathcal{B}$ , if  $\varphi(\varphi(X|\mathcal{B})S) = \varphi(XS)$  for all  $X \in \mathcal{B}'$  and  $S \in \mathcal{B}$ .

# Quantum conditional expectation

## Lemma : existence and uniqueness of conditional expectation

For any commutative von Neumann algebra  $\mathcal{B}$  and  $X \in \mathcal{B}'$ , the conditional expectation  $\varphi(X|\mathcal{B})$  exists and is unique  $\varphi$ -a.s.

*Proof.*

### ■ Existence

- $X \in \mathcal{B}'$  is self-adjoint (classical conditional exp., spectral theorem)
- $X \in \mathcal{B}'$  is not self-adjoint,  $X = (X + X^*)/2 + i(X - X^*)/2i$

### ■ Uniqueness

- Let  $A$  and  $B$  be two versions of  $\varphi(X|\mathcal{B}) \Rightarrow A - B \in \mathcal{B}$  and  $A \in \mathcal{B}'$
- $\varphi((A - B)^*(A - B)) = \|A - B\|_{\varphi} = 0$ .

# Quantum conditional expectation

## Lemma : optimal estimation

For any  $X \in \mathcal{B}'$ ,  $\|X - \varphi(X|\mathcal{B})\|_{\varphi} = \min_{Y \in \mathcal{B}} \|X - Y\|_{\varphi}$ .

*Proof.*

$$\begin{aligned}\|X - Y\|_{\varphi}^2 &= \|X - \varphi(X|\mathcal{B}) + \varphi(X|\mathcal{B}) - Y\|_{\varphi}^2 \\ &= \|X - \varphi(X|\mathcal{B})\|_{\varphi}^2 + \|\varphi(X|\mathcal{B}) - Y\|_{\varphi}^2 \\ &\geq \|X - \varphi(X|\mathcal{B})\|_{\varphi}^2, \quad \forall Y \in \mathcal{B}.\end{aligned}$$

# Quantum Bayes formula

## Theorem : quantum Bayes formula

Let  $(\mathcal{A}, \varphi)$  be a quantum probability space,  $\mathcal{B} \subset \mathcal{A}$  be a commutative von Neumann subalgebra. Choose  $V \in \mathcal{B}'$  s.t.  $V^*V > 0$  and  $\varphi(V^*V) = 1$ . Then we can define a new state  $\varpi$  on  $\mathcal{B}'$  by  $\varpi(X) := \varphi(V^*XV)$ , and

$$\varpi(X|\mathcal{B}) = \frac{\varphi(V^*XV|\mathcal{B})}{\varphi(V^*V|\mathcal{B})}, \quad \forall X \in \mathcal{B}'.$$

*Proof.*

$$\begin{aligned} \varphi(\varphi(V^*XV|\mathcal{B})K) &= \varphi(V^*XVK) = \varphi(V^*XKV) = \varpi(XK) = \varpi(\varpi(X|\mathcal{B})K) \\ &= \varphi(V^*\varpi(X|\mathcal{B})KV) = \varphi(V^*V\varpi(X|\mathcal{B})K) = \varphi(\varphi(V^*V\varpi(X|\mathcal{B})K|\mathcal{B})) \\ &= \varphi(\varphi(V^*V|\mathcal{B})\varpi(X|\mathcal{B})K), \quad \forall X \in \mathcal{B}', K \in \mathcal{B}. \end{aligned}$$

# Conditional expectation for unbounded observables

## Definition : quantum conditional expectation

Let  $(\mathcal{A}, \varphi)$  be a quantum probability space and  $\mathcal{B} \subset \mathcal{A}$  be a commutative von Neumann subalgebra. Let  $X \in \mathcal{A}$  be self-adjoint and suppose  $\varphi(|X|) < \infty$ . Then any self-adjoint operator  $\varphi(X|\mathcal{B}) \in \mathcal{B}$  satisfying  $\varphi(\varphi(X|\mathcal{B})\hat{S}) = \varphi(X\hat{S})$  for all  $S \in \mathcal{B}$  is called (a version of) the conditional expectation  $X$  given  $\mathcal{B}$ .

## Remark :

- $\mathcal{S}(\text{vN}(X, \mathcal{B}))$  forms a commutative  $*$ -algebra (with unit  $\mathbb{1}$ ) under  $\hat{+}$  and  $\hat{\cdot}$ .<sup>1</sup>
- Existence+uniqueness is ensured by classical condit. exp.+spectral thm

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1. J. R. Ringrose, R. V. Kadison, "Fundamentals of the theory of operator algebras, pp 351-356", Vol 1, AMS, 1983.

# Bayes formula (unbounded observables)

## Motivation

Change-of-state operator  $V$  in Quantum Bayes formula may be **unbounded**

### Settings for joint system :

- Hilbert space  $\mathcal{H} = \mathcal{H}_S \otimes \mathcal{H}_R$ ,  $\dim(\mathcal{H}_S) = N < \infty$  and  $\mathcal{H}_R$  is separable
- $\mathcal{A} = \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}(\mathcal{H}_R)$ , the normal state  $\varphi = \varphi_S \otimes \varphi_R$
- Quantum probability space  $(\mathcal{A}, \varphi)$
- $\mathcal{B}_R \subset \mathcal{B}(\mathcal{H}_R)$  : a commutative von Neumann subalgebra
- $\mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R \subset (\mathbb{1} \otimes \mathcal{B}_R)'$

# Bayes formula (unbounded observables)

- 1  $\mathcal{B}(\mathcal{H}_S) \simeq \mathcal{M}_N(\mathbb{C})$  with  $\dim(\mathcal{H}_S) = N < \infty$
- 2  $\varphi_S(X_S) = \text{Tr}(\rho X_S)$ ,  $\forall X_S \in \mathcal{M}_N(\mathbb{C})$ , where  $\rho$  is a density operator
- 3  $\mathcal{A} \simeq \mathcal{M}_N(\mathcal{B}(\mathcal{H}_R))$ , the algebra of  $N \times N$  matrices with  $\mathcal{B}(\mathcal{H}_R)$ -valued entries,

$$X = \begin{bmatrix} X_{11} & \cdots & X_{1N} \\ \vdots & \ddots & \vdots \\ X_{N1} & \cdots & X_{NN} \end{bmatrix} \in \mathcal{A}, \quad X_{ij} \in \mathcal{B}(\mathcal{H}_R),$$

- 4 the state  $\varphi$  on  $\mathcal{A}$  can be represented by

$$\varphi(X) = \text{Tr} \left( \rho \begin{bmatrix} \varphi_R(X_{11}) & \cdots & \varphi_R(X_{1N}) \\ \vdots & \ddots & \vdots \\ \varphi_R(X_{N1}) & \cdots & \varphi_R(X_{NN}) \end{bmatrix} \right)$$

- 5 partial state of  $\varphi^1 : \varphi_R(X) \in \mathcal{M}_N(\mathbb{C})$  and  $\varphi_S(X) \in \mathcal{B}(\mathcal{H}_R)$ , for all  $X \in \mathcal{A}$
- 6  $\varphi(X) = \varphi_S(\varphi_R(X)) = \varphi_R(\varphi_S(X))$

# Bayes formula (unbounded observables)

- 1  $\mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R \simeq \mathcal{M}_N(\mathcal{B}_R)$
- 2  $\mathcal{N}(\mathcal{B}_R)$  : set of normal operators affiliated to  $\mathcal{B}_R \Rightarrow$   $*$ -algebra under  $\hat{+}$  and  $\hat{\cdot}$
- 3  $\mathcal{M}_N(\mathcal{N}(\mathcal{B}_R))$  forms  $*$ -algebra under extension of  $\hat{+}$  and  $\hat{\cdot}$

## Theorem : quantum Bayes formula <sup>1</sup>

Let  $V \in \mathcal{M}_N(\mathcal{N}(\mathcal{B}_R))$  satisfying  $\varphi(V^*V) = 1$ . For  $X \in \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R$ , define  $\varpi(X) = \varphi(V^* \hat{\cdot} X \hat{\cdot} V)$ . Then  $\varpi$  is a normal state on  $\mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R$ . Moreover, if  $V^*V > 0$ , then

$$\varpi(X | \mathbb{1} \otimes \mathcal{B}_R) = \mathbb{1} \otimes \frac{\varphi_S(V^* \hat{\cdot} X \hat{\cdot} V)}{\varphi_S(V^*V)}, \quad \forall X \in \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R.$$

1. R. van Handel, "Filtering, stability, and robustness, pp 107-108", Ph.D. Thesis, 2007



# Quantum filtering theory

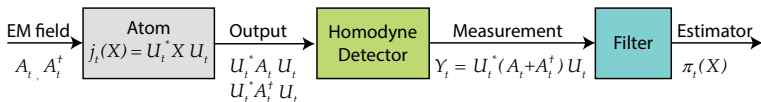
## Quantum filtering theory

### References :

- 1 R. van Handel, "*Filtering, stability, and robustness*", Ph.D. Thesis, 2007.
- 2 L. Bouten, R. van Handel, M. James, "*An introduction to quantum filtering*", SIAM. J. Control Optim, 2007.
- 3 L. Bouten, R. van Handel, "*On the separation principle in quantum control*", Quantum Stoch. Inf. (pp. 206-238), 2008.
- 4 L. Accardi, Y. G. Lu, I. Volovich, "*Quantum theory and its stochastic limit, Ch 6*", Springer, 2002.
- 5 V. P. Belavkin, "*Quantum stochastic calculus and quantum nonlinear filtering*", Journal of Multivariate analysis, 1992.

# Quantum filtering setup

- $\varphi_R$  is state on  $\mathcal{B}_{\mathbb{R}_+}$  is vacuum state  $\langle e(0), \cdot e(0) \rangle$
- $\varphi_S$  is state on  $\mathcal{B}(\mathcal{H}_S)$ , finite convex combination of  $\langle v, \cdot v \rangle$  with  $v \in \mathcal{H}_S$ .
- $\mathcal{A} = \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}(\Gamma_s(L^2(\mathbb{R}_+)))$  with  $\dim(\mathcal{H}_S) = N < \infty$ ,  $\varphi = \varphi_S \otimes \varphi_R$
- quantum probability space  $(\mathcal{A}, \varphi)$



- self-nondemolition property  $\Rightarrow Y_t$  can be observed in a realization
- nondemolition property  $\Rightarrow \pi_t(X) := \varphi(j_t(X) | \mathcal{Y}_t)$  is well defined

## Objective of quantum filtering

Obtain an explicit expression of  $\pi_t(X)$  in terms of the observations  $\{Y_s\}_{0 \leq s \leq t}$ .

# Change of state

## Lemma

For all  $X \in \mathcal{B}(\mathcal{H}_S) \otimes \mathbb{1}$ , define  $\bar{\omega}_t(X) = \varphi(U_t^* X U_t)$ , then

$$\varphi(j_t(X)|\mathcal{Y}_t) = U_t^* \bar{\omega}_t(X|Z_t) U_t, \quad \varphi - a.s.$$

*Proof.*

For any  $S \in Z_t$ , then  $U_t^* S U_t \in \mathcal{Y}_t = U_t^* Z_t U_t$ ,

$$\varphi(U_t^* \bar{\omega}_t(X|Z_t) U_t U_t^* S U_t) = \bar{\omega}_t(\bar{\omega}_t(X|Z_t) S) = \bar{\omega}_t(XS) = \varphi(U_t^* X U_t U_t^* S U_t).$$

**Remark :**

- We should apply Bayes formula (bounded ) for  $\bar{\omega}_t(X|Z_t)$
- $\bar{\omega}(X|Z_t) = \varphi(U_t^* X U_t | Z_t) / \varphi(U_t^* U_t | Z_t)$  with  $U_t \in Z_t'$
- If  $U_t \in Z_t'$ ,  $Y_t = U_t^* Z_t U_t = Z_t \Rightarrow$  system does not interact with field
- We cannot use  $U_t$  as change-of-state operator

## Objective

Find  $V_t \in \mathcal{M}_N(\mathcal{N}(Z_t))$  s.t.  $\varphi(U_t^* X U_t) = \varphi(V_t^* \hat{X} V_t)$  for all  $X \in \mathcal{B}(\mathcal{H}_S) \otimes Z_t$

# Change-of-state operator

## Lemma

Let  $D_t$ ,  $F_t$ ,  $\tilde{F}_t$  and  $G_t$  be bounded processes, and let

$$dV_t = (D_t dA_t^\dagger + F_t dA_t + G_t dt) V_t, \quad d\tilde{V}_t = (D_t dA_t^\dagger + \tilde{F}_t dA_t + G_t dt) \tilde{V}_t,$$

where  $V_0 = \tilde{V}_0$ . Then  $V_t v \otimes e(0) = \tilde{V}_t v \otimes e(0)$  for all  $v \in \mathcal{H}_S$ .

*Proof.*

- $V_t$  and  $\tilde{V}_t$  are uniquely defined admissible adapted processes
- $\|(V_t - \tilde{V}_t)v \otimes e(0)\|^2 \leq C_T \int_0^t \|(V_s - \tilde{V}_s)v \otimes e(0)\|^2 ds$ , with  $t < T < \infty$
- Gronwall inequality implies  $\|(V_t - \tilde{V}_t)v \otimes e(0)\|^2 = 0$

**Consequence :**

$\varpi_t(X) = \varphi(U_t^* X U_t) = \langle U_t v \otimes e(0), X U_t v \otimes e(0) \rangle = \langle V_t v \otimes e(0), X V_t v \otimes e(0) \rangle$ , where

$$dU_t = (L_t dA_t^\dagger - L_t^* dA_t - \frac{1}{2} L_t L_t^* dt - iH_t dt) U_t, \quad U_0 = \mathbb{1}$$

$$dV_t = (L_t (dA_t^\dagger + dA_t) - \frac{1}{2} L_t L_t^* dt - iH_t dt) V_t, \quad V_0 = \mathbb{1}$$

$dA_t e(0) = 0 \Rightarrow$  **change of  $A_t$ -integral will not affect the impact of QSDE on vacuum**

# Change-of-state operator in vacuum state

## Principal idea : <sup>1 2 3</sup>

1  $Z_t \xleftrightarrow{\text{spectral thm}} z_t = \iota(Z_t)$  classical Brownian motion

2  $dV_t = (L_t(dA_t^\dagger + dA_t) - \frac{1}{2}L_tL_t^*dt - iH_tdt)V_t \xleftrightarrow{\text{spectral thm}}$  matrix-valued Itô SDE

3  $V_t := \iota^{-1}$ (solution of SDE)  $\in \mathcal{M}_N(\mathcal{N}(Z_t))$  is target change-of-state operator

4 new  $V_t$  and old  $V_t$  have same action on **vacuum vector**

5 
$$\left. \begin{array}{l} \text{spectral theorem} \\ V_t v \otimes e(0) = U_t v \otimes e(0) \end{array} \right\} \Rightarrow \varphi(U_t^* X U_t) = \varphi(V_t^* \hat{X} V_t)$$

1. R. van Handel, "Filtering, stability, and robustness, pp 112-113", Ph.D. Thesis, 2007.

2. L. Accardi, Y. G. Lu, I. Volovich, "Quantum theory and its stochastic limit, Ch 6.3", 2002.

3. R. L. Hudson, K. R. Parthasarthy, "Quantum Ito's formula and stochastic evolution, Sec 5".

# Change-of-state operator in vacuum state

- $(\Omega, \mathcal{G}, \mu), \mathfrak{v} : \text{obtained by applying spectral thm on } Z_t$
- $z_t = \mathfrak{v}(Z_t), L_t = L_t \otimes \mathbb{1}$  and  $H_t = H_t \otimes \mathbb{1}$  are bounded process

## Lemma<sup>1</sup>

Let  $v_t$  be the solution of the matrix-valued Itô SDE,

$$dv_t = (L_t dz_t - \frac{1}{2} L_t L_t^* dt - iH_t dt)v_t, \quad v_0 = \mathbb{1}.$$

Then  $V_t$  coincides with  $\mathfrak{v}^{-1}(v_t) \in \mathcal{M}_N(\mathcal{N}(Z_t))$  at least on a dense subdomain  $\mathcal{H}_S \otimes \mathcal{E}' \subset \mathcal{H}_S \otimes \mathcal{E}$  which contains all vectors of the form  $v \otimes e(0)$ .

- Identify  $V_t$  with  $\mathfrak{v}^{-1}(v_t)$

## Lemma<sup>1</sup>

$\mathfrak{w}_t(X) = \varphi(U_t^* X U_t) = \varphi(V_t^* \hat{X} V_t)$  for all  $X \in \mathcal{B}(\mathcal{H}_S) \otimes Z_t$ .

1. R. van Handel, "Filtering, stability, and robustness, pp 112-113", Ph.D. Thesis, 2007.

# Quantum Kallianpur-Striebel formula (Bayes formula)

## Theorem : quantum Bayes formula

Let  $V \in \mathcal{M}_N(\mathcal{N}(\mathcal{B}_R))$  satisfying  $\varphi(V^*V) = 1$ . For  $X \in \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R$ , define  $\bar{\omega}(X) = \varphi(V^* \hat{X} V)$ . Then  $\bar{\omega}$  is a normal state on  $\mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R$ . Moreover, if  $V^*V > 0$ , then

$$\bar{\omega}(X | \mathbb{1} \otimes \mathcal{B}_R) = \mathbb{1} \otimes \frac{\varphi_S(V^* \hat{X} V)}{\varphi_S(V^* V)}, \quad \forall X \in \mathcal{B}(\mathcal{H}_S) \otimes \mathcal{B}_R.$$

## Theorem : quantum Kallianpur-Striebel formula

For all  $X \in \mathcal{B}(\mathcal{H}_S)$ ,  $\pi_t(X) = U_t^* \bar{\omega}_t(X \otimes \mathbb{1} | \mathcal{Z}_t) U_t$ , where

$$\bar{\omega}_t(X \otimes \mathbb{1} | \mathcal{Z}_t) = \mathbb{1} \otimes \frac{\varphi_S(V_t^* \hat{(X \otimes \mathbb{1})} V_t)}{\varphi_S(V_t^* V_t)}.$$

- $v_t$  is invertible<sup>1</sup>  $\Rightarrow V_t^* V_t > 0$
- $\varphi_S$  is finite convex combination of  $\langle v, \cdot v \rangle$  with  $v \in \mathcal{H}_S$ .

1. P. E. Protter, "Stochastic Integration and Differential Equations, pp 326", Springer, 2005.

# Quantum Kallianpur-Striebel formula (Bayes formula)

- $(\Omega, \mathcal{F}, \mu)$ ,  $\nu$  : obtained by applying spectral thm on  $\mathcal{Y}_T = U_T^* Z_T U_T$
- $\mathbb{P}$  : probability measure on  $\mathcal{F}$  induced by  $\varphi$
- $y_t = \nu(Y_t)$ ,  $L_t = L_t \otimes \mathbb{1}$  and  $H_t = H_t \otimes \mathbb{1}$  are bounded process

## Lemma<sup>1</sup>

Let  $\bar{v}_t$  for  $t \in [0, T]$  be the solution of the matrix-valued Itô SDE,

$$d\bar{v}_t = (L_t dy_t - \frac{1}{2} L_t L_t^* dt - iH_t dt) \bar{v}_t, \quad \bar{v}_0 = \mathbb{1}.$$

For any  $X \in \mathcal{B}(\mathcal{H}_S)$ , define  $\bar{\sigma}_t(X) := \varphi_S(\bar{v}_t^* X \bar{v}_t)$ ,  $\bar{\pi}_t(X) := \bar{\sigma}_t(X) / \bar{\sigma}_t(\mathbb{1})$ . Then,

- $\bar{\pi}_t(X) = \nu(\pi_t(X))$ ,
- $\{y_t\}_{t \in [0, T]}$  is a Brownian motion under  $\mathbb{Q}$  s.t.  $d\mathbb{P} = \bar{\sigma}_T(\mathbb{1}) d\mathbb{Q}$ .

1. R. van Handel, "Filtering, stability, and robustness, pp 112-113", Ph.D. Thesis, 2007.



# Input-output model for homodyne detection

## Outline of proof.

- $\iota_Z : \mathcal{Z}_T \rightarrow L^\infty(\Omega_Z, \mathcal{F}_Z, \mu_Z)$ ,  $\iota_Y : \mathcal{Y}_T \rightarrow L^\infty(\Omega_Y, \mathcal{F}_Y, \mu_Y)$
- $\iota : \mathcal{Y}_T \rightarrow L^\infty(\Omega_Y, \mathcal{F}_Y, \mu_Y)$  acts as  $\iota(X) = \iota_Z(U_T X U_T^*)$
- probability measure on  $\mathcal{F}_Z : \mathbb{E}^{\mathbb{P}}(\iota(X_Y)) = \varphi(X_Y)$ ,  $\mathbb{E}^{\mathbb{Q}}(\iota_Z(X_Z)) = \varphi(X_Z)$
- $y_t = \iota(Y_t) = \iota_Z(Z_t) = z_t : y_t$  is Brownian motion under  $\mathbb{Q}$
- $\iota(\pi_t(X)) = \iota_Z(\varpi_t(X \otimes \mathbb{1} | \mathcal{Z}_t)) = \iota_Z(\mathbb{1} \otimes \frac{\varphi_S(V_t^* \hat{\iota}(X \otimes \mathbb{1}) \hat{\iota}(V_t))}{\varphi_S(V_t^* V_t)}) = \bar{\pi}_t(X)$
- For any functional  $F_Y$  of  $\{y_t\}$ ,

$$\mathbb{E}^{\mathbb{P}}(F_Y) = \varpi_T(\iota_Z^{-1}(F_Y)) = \varphi(V_T^* \hat{\iota}_Z^{-1}(F_Y) \hat{\iota}(V_T)) = \mathbb{E}^{\mathbb{Q}}(\varphi_S(V_t^* V_t) F_Y)$$

# Innovations process

- $(\Omega, \mathcal{F}, \mu), \nu$  : obtained by applying spectral thm on  $\mathcal{Y}_T = U_T^* Z_T U_T$
- $\mathbb{P}$  : probability measure on  $\mathcal{F}$  induced by  $\varphi$
- $y_t = \nu(Y_t), L_t = L_t \otimes \mathbb{1}$  is bounded process
- $\bar{\sigma}_t(X) := \varphi_S(\bar{v}_t^* X \bar{v}_t), \bar{\pi}_t(X) := \bar{\sigma}_t(X) / \bar{\sigma}_t(\mathbb{1})$

## Lemma

The innovations process  $\hat{z}_t := y_t - \int_0^t \pi(L_s + L_s^*) ds$  is a Brownian motion under  $\mathbb{P}$ .

*Proof.*

- 1 Itô formula :  $d\bar{\sigma}_t(\mathbb{1}) = \bar{\sigma}_t(L_t + L_t^*) dy_t = \bar{\pi}_t(L_t + L_t^*) \bar{\sigma}_t(\mathbb{1}) dy_t$
- 2  $\bar{\sigma}_t(\mathbb{1})$  is Girsanov transformation

# Quantum Kushner-Stratonovich equation

Theorem : quantum Kushner-Stratonovich equation

$\bar{\sigma}_t(X)$  and  $\bar{\pi}_t(X)$  satisfy

$$d\bar{\sigma}_t(X) = \bar{\sigma}_t(\mathcal{L}_t^*(X))dt + \bar{\sigma}_t(L^*X + XL)dy_t,$$

$$d\bar{\pi}_t(X) = \bar{\pi}_t(\mathcal{L}_t^*(X))dt + (\bar{\pi}_t(L^*X + XL) - \bar{\pi}_t(L^* + L)\bar{\pi}_t(X))d\bar{z}_t,$$

where  $\bar{\sigma}_0(X) = \bar{\pi}_0(X) = \varphi_S(X)$  and  $\mathcal{L}_t^*(X) := i[H_t, X] + L_t^*XL_t - \frac{1}{2}L_t^*L_tX - \frac{1}{2}XL_t^*L_t$ .

Theorem : stochastic master equation

Let  $\rho_t$  be the random density matrix satisfying  $\bar{\pi}_t(X) = \text{Tr}(\rho_t X)$ . Then  $\rho_t$  satisfies

$$d\rho_t = \mathcal{L}_t(\rho_t)dt + (L\rho_t + \rho_t L^* - \text{Tr}((L_t + L_t^*)\rho_t)\rho_t)(dy_t - \text{Tr}((L_t + L_t^*)\rho_t)dt),$$

where  $\rho_0 = \rho$  and  $\mathcal{L}_t(\rho) := i[\rho, H_t] + L_t\rho L_t^* - \frac{1}{2}L_t^*L_t\rho - \frac{1}{2}\rho L_t^*L_t$ .

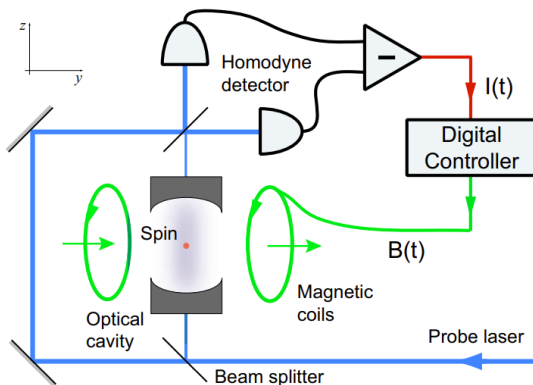
Theorem : quantum Zakai equation

Let  $\zeta_t$  be the random nonnegative self-adjoint matrix s.t.  $\bar{\sigma}_t(X) = \text{Tr}(\zeta_t X)$ . Then,

$$d\zeta_t = \mathcal{L}_t(\rho_t)dt + (L\zeta_t + \rho_t L^*)dy_t, \quad \zeta_0 = \rho.$$

Moreover,  $\rho_t = \zeta_t / \text{Tr}(\zeta_t)$ .

# Quantum feedback control



**FIGURE** – Experiment setup for feedback control of spin system, which interacts with an optical field measured continuously by homodyne detection. A magnetic field is used for the feedback<sup>1</sup>.

1. R. van Handel, J.K. Stockton, H.Mabuchi, IEEE TAC, 2005.